Semantics

Type System

Conclusion

If you are in a hurry

SPOILER WARNING: Plot and/or ending details follow.

$$\frac{-}{\emptyset \vdash \mathbf{0}} (\mathrm{NIL}) \frac{A \vdash_{\pi} P A \leq A'}{A' \vdash_{\pi} P A' \vdash_{p} P} (\mathrm{WEAK}) \frac{A \vdash_{\pi} P}{!A \vdash_{\pi} !P} (\mathrm{REP})$$

$$\frac{i = 1, 2 : A_{i} \vdash_{\pi} P_{i}}{A_{1} \odot A_{2} \vdash_{\pi} P_{1} \mid P_{2}} (\mathrm{PAR}) \frac{A \vdash_{\pi} P}{(\nu x) A \vdash_{\pi} (\nu x) P} (\mathrm{RES})$$

$$\frac{A \vdash_{\pi} P \forall !: \mathbf{md}(\Sigma_{A}(l)) \notin \{\downarrow_{1},\uparrow_{1},\downarrow_{\omega_{0}}\}}{\rho.(\nu \tilde{x}) (\rho : ((\tilde{\sigma})^{\mathbb{P}}, \rho) + \rho(\tilde{x} : \tilde{\sigma}) \odot A) \vdash_{p} \rho(\tilde{x}).P} (\mathrm{INP}_{p})$$

$$\frac{A \vdash_{\pi} P}{(\nu \tilde{x}) (l : ((\tilde{\sigma})^{\downarrow_{1}}, \rho, \emptyset, (\tilde{x})) + l.\hat{l}.\rho(\tilde{x} : \tilde{\sigma}) \odot l.A) \vdash_{\pi} l(\tilde{x}).P} (\mathrm{INP}_{u})$$

$$\frac{A \vdash_{\pi} P}{(\nu \tilde{x}) (u : ((\tilde{\sigma})^{\downarrow_{\omega_{0}}}, \rho, \emptyset, (\tilde{x})) + u.\rho(\tilde{x} : \tilde{\sigma}) \odot u.A) \vdash u(\tilde{x}).P} (\mathrm{INP}_{\omega})$$

$$\frac{A \vdash_{\pi} P}{\rho. (\rho : ((\tilde{\sigma})^{\mathbb{P}}, \rho) + \bar{\rho}(\tilde{x} : \tilde{\sigma}) \odot A) \vdash_{p} \bar{p}(\tilde{x}).P} (\mathrm{OuT}_{p})$$

$$\frac{A \vdash_{\pi} P}{l : ((\tilde{\sigma})^{\uparrow_{1}}, \rho, \emptyset, \emptyset, (\tilde{x})) + l.\tilde{l}.\tilde{\rho}(\tilde{x} : \tilde{\sigma}) \odot l.A \vdash_{\pi} \bar{l}(\tilde{x}).P} (\mathrm{OuT}_{1})$$

$$\frac{A \vdash_{\pi} P}{l : ((\tilde{\sigma})^{\uparrow_{1}}, \rho, \emptyset, \emptyset, (\tilde{x})) + l.\tilde{l}.\tilde{\rho}(\tilde{x} : \tilde{\sigma}) \odot u.A \vdash_{\pi} \bar{u}(\tilde{x}).P} (\mathrm{OuT}_{\omega})$$

Deciding Deterministic Responsiveness and Closeness in π -calculus

Maxime Gamboni

Insituto Superior Técnico

June 27, 2006

Teach Yourself Polyadic π -Calculus in 4 Minutes (I)

- Model for Communication & Concurrency
- Based around Named Channels

Teach Yourself Polyadic π -Calculus in 4 Minutes (I)

- Model for Communication & Concurrency
- Based around Named Channels

Two kinds of things are done in π .

- Sending something (ξ) over a channel (a): $\overline{a}\langle\xi\rangle$.P
- Receiving something on a channel (a), and referring to it as x afterwards: a(x).P

Teach Yourself Polyadic π -Calculus in 4 Minutes (II)

• Some other constructs: $P_1|P_2$, $(\nu x) P$, !P, **0** E.g. $\overline{a}\langle s \rangle \mid a(x).\overline{x} \rightarrow \mathbf{0} \mid \overline{s}$

Teach Yourself Polyadic π -Calculus in 4 Minutes (II)

- Some other constructs: $P_1|P_2$, $(\nu x)P$, !P, $\mathbf{0}$
- E.g. $\overline{a}\langle s \rangle \mid a(x).\overline{x} \rightarrow \mathbf{0} \mid \overline{s}$
 - *POLY*-adic: More than one name can be moved around at a time

E.g. $\overline{a}\langle x, y, z \rangle$. P

• Higher level languages can be *encoded* into π :

$$\llbracket \overline{a}\langle \xi \rangle \rrbracket \stackrel{\text{def}}{=} \overline{a}\langle u \rangle \underbrace{! u(\tilde{r}) \cdots}_{\text{server for } \xi}$$

• Higher level languages can be *encoded* into π :

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• We want Full Abstraction:

 $(P \approx Q) \iff (\llbracket P \rrbracket \approx_{\mathsf{R}} \llbracket Q \rrbracket)$

\approx_{R} is not a Regular Bisimulation

• These two (high level) processes are *bisimilar* $P = a(b).if(b)(if(\neg b) print OOPS; else print OK;)$ Q = a(b).print OK;

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 - We also need to enforce:

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Determinism,

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Determinism, Closeness, Responsiveness

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- $P = a(b).if(b)(if(\neg b) \text{ print } OOPS; \text{ else print } OK;)$ Q = a(b).print OK;
 - Yet their encoded forms are not.
 - We also need to enforce:

Determinism, Closeness, Responsiveness and Uniformity.

Names in an encoded process (and its environment) are separated in three groups.

• For encoded data:

 ω -names

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• For encoded data:

 ω -names

• For responsiveness:

linear names

Names in an encoded process (and its environment) are separated in three groups.

• For encoded data:

 ω -names

• For responsiveness:

linear names

• For the rest:

plain names

Templates and Observability

Two constructs are needed for defining bisimilarity:

Definition

Template Processes $L_{\sigma}(a)$: Models ω -servers in the environment.

$$\mathsf{L}_{\left((\mathfrak{p})^{\uparrow_{1}}\right)^{\downarrow_{\omega}}}(a) = ! a(x).\overline{x}\langle a_{1}\rangle$$

Templates and Observability

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Definition

Template Processes $L_{\sigma}(a)$: Models ω -servers in the environment.

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Definition

Observable Data $\Omega_P^{\Sigma}(a)$: Tests ω -servers in the process.

If $P = ! a(x).\overline{x}\langle z \rangle$ then $\Omega_P^{\Sigma}(a) = \langle z \rangle$

Symmetric \mathcal{R} is a *discreet* bisimulation if $P\mathcal{R}Q$ implies:

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$$Q \stackrel{\hat{\mu}}{\Longrightarrow} Q'$$
 and $P'\mathcal{R}Q'$.

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$$\forall u \ \omega \text{-input in } P \text{ (say } P \xrightarrow{u(\tilde{x})} P') \\ \bullet \ \Omega_P^{\Sigma}(u) = \Omega_Q^{\Sigma}(u),$$

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$$\forall u \ \omega \text{-input in } P \text{ (say } P \xrightarrow{u(\tilde{x})} P') \\ \bullet \ \Omega_P^{\Sigma}(u) = \Omega_Q^{\Sigma}(u), \\ \bullet \text{ Safety: } P'\mathcal{R}P',$$

Symmetric \mathcal{R} is a *discreet* bisimulation if $P\mathcal{R}Q$ implies:

• If $P \xrightarrow{\mu} P'$ where μ is silent or on a plain/linear channel:

•
$$Q \stackrel{\hat{\mu}}{\Longrightarrow} Q'$$
 and $P'\mathcal{R}Q'$.

•
$$\Omega_P^{\Sigma}(u) = \Omega_Q^{\Sigma}(u)$$
,

- Safety: $P'\mathcal{R}P'$,
- Determinism: $\exists \xi \text{ s.t. } \Omega_P^{\Sigma}(u) = \xi$,

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 - Closeness: $P\mathcal{R}(\nu \tilde{x}) P'$.

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 - Safety: $P'\mathcal{R}P'$,
 - Determinism: $\exists \xi \text{ s.t. } \Omega_P^{\Sigma}(u) = \xi$,
 - Closeness: $P\mathcal{R}(\nu \tilde{x}) P'$.
- **●** $\forall u$ *ω*-output in *P*:
 - $(L_{\sigma}(u) | P) \mathcal{R} Q$.

Definition

A Channel Type is a structure of the form:

 $a: ((ilde{\sigma})^m,
ho, ilde{lpha}, ilde{eta}, ilde{\gamma})$

- $\tilde{\sigma}$: Parameters
- m: Action Mode
- ho: Protocol
- $\tilde{\alpha}$: Receptiveness
- $\tilde{\beta}$: Input Responsiveness
- $\tilde{\gamma}$: Output Responsiveness

Highly constrained ω and unreliable plain names can interact.

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$$(\boldsymbol{\nu} p) \left(\overline{p} \langle u \rangle ! u \cdots \mid \overline{p} \langle v \rangle ! v \cdots \mid p(x) \cdots \mid p(y) \cdots \right)$$

Highly constrained ω and unreliable plain names can interact.



- $(\boldsymbol{\nu} p) \left(\overline{p} \langle u \rangle ! u \cdots | \overline{p} \langle v \rangle ! v \cdots | p(x) \cdots | p(y) \cdots \right)$
 - p over ω :

 $\overline{u}\langle l, p, q \rangle \mid ! u(x, y, z).\overline{x}\langle y \rangle$

Highly constrained ω and unreliable plain names can interact.



- $(\boldsymbol{\nu} p) \left(\overline{p} \langle u \rangle ! u \cdots | \overline{p} \langle v \rangle ! v \cdots | p(x) \cdots | p(y) \cdots \right)$
 - p over ω :
- $\overline{u}\langle l, p, q \rangle \mid ! u(x, y, z).\overline{x}\langle y \rangle$
 - Still, ω 's discreetness guarantees are preserved.

Semantics

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Conclusion

$$\frac{A \vdash_{\pi} P}{(\nu \tilde{x}) \left(l : (\downarrow_1)((\tilde{\sigma})^{\downarrow_1}, \rho, \emptyset, (\tilde{x})) + l.\hat{l}.\rho(\tilde{x} : \tilde{\sigma}) \odot l.A \right) \vdash_{\pi} l(\tilde{x}).P} (\text{INP}_1)$$

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Anatomy of one Rule

$$\frac{A \vdash_{\pi} P}{(\nu \tilde{x}) \left(l: (\downarrow_1)((\tilde{\sigma})^{\downarrow_1}, \rho, \emptyset, (\tilde{x})) + l.\hat{l}.\rho(\tilde{x}:\tilde{\sigma}) \odot l.A \right) \vdash_{\pi} l(\tilde{x}).P} (INP_1)$$

• *I* receptive now; responsive when parameters are ready

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Semantics

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$$\frac{A \vdash_{\pi} P}{(\boldsymbol{\nu}\tilde{x}) \left(I: (\downarrow_1)((\tilde{\sigma})^{\downarrow_1}, \rho, \emptyset, (\tilde{x})) + I.\hat{I}.\rho(\tilde{x}:\tilde{\sigma}) \odot I.A \right) \vdash_{\pi} I(\tilde{x}).P} (INP_1)$$

- I receptive now; responsive when parameters are ready
- Remote parameters

_

$$\frac{A \vdash_{\pi} P}{(\boldsymbol{\nu}\tilde{x}) \left(I: (\downarrow_1)((\tilde{\sigma})^{\downarrow_1}, \rho, \emptyset, (\tilde{x})) + I.\hat{I}.\rho(\tilde{x}:\tilde{\sigma}) \odot I.A \right) \vdash_{\pi} I(\tilde{x}).P} (INP_1)$$

- I receptive now; responsive when parameters are ready
- Remote parameters
- Continuation

Semantics

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$$\frac{A \vdash_{\pi} P}{(\boldsymbol{\nu} \tilde{\boldsymbol{x}}) \left(I : (\downarrow_{1})((\tilde{\sigma})^{\downarrow_{1}}, \rho, \emptyset, (\tilde{\boldsymbol{x}})) + I.\hat{I}.\rho(\tilde{\boldsymbol{x}} : \tilde{\sigma}) \odot I.A \right) \vdash_{\pi} I(\tilde{\boldsymbol{x}}).P} (\text{INP}_{1})$$

- I receptive now; responsive when parameters are ready
- Remote parameters
- Continuation
- P must provide resources specified in $\tilde{\sigma}$

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(Expected) Results

Discreetness:

Theorem

$$(A \vdash_{\pi} P) \Rightarrow (P \approx_{\mathsf{R}} P)$$

(Expected) Results

Discreetness:

Theorem

$$(A \vdash_{\pi} P) \Rightarrow (P \approx_{\mathsf{R}} P)$$

Soundness:

Theorem

$$(A \vdash_{\pi} P) \land \Sigma_{A}(a) = (\cdots)^{\uparrow_{1}} \Rightarrow (P \xrightarrow{(\nu \tilde{z}) \ \overline{a}\langle \tilde{x} \rangle})$$
$$(A \vdash_{\pi} P) \land \Sigma_{A}(a) = (\cdots)^{\downarrow_{1}} \Rightarrow (P \xrightarrow{a(\tilde{x})})$$

(Expected) Results

Discreetness:

Theorem

$$(A \vdash_{\pi} P) \Rightarrow (P \approx_{\mathsf{R}} P)$$

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$$(A \vdash_{\pi} P) \land \Sigma_{A}(a) = (\cdots)^{\downarrow_{1}} \Rightarrow (P \xrightarrow{a(\tilde{x})})$$

Safety:

Theorem

$$(A \vdash_{\pi} P) \land (P \rightarrow P') \Rightarrow (A \vdash_{\pi} P')$$

Thank You (Obrigado, Shukria, Kiitos, Merci)!

The paper can be found at http://gamboni.org/maxime/